

ENE4014: Programming Languages

Lecture 16 — Let-Polymorphic Type System

Woosuk Lee
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Motivation

- Our type system is useful but it is not as expressive as we would like it to be. In particular, it does not support *polymorphism*¹. For example, it rejects the following program:

```
let f = proc (x) x in
  if (f (iszero (0))) then (f 11) else (f 22)
```

- Polymorphic functions are widely used in practice, so OCaml supports polymorphism:

```
# let f = fun x -> x in
  if (f (0=0)) then (f 11) else (f 22);;
- : int = 11
```

- Lets extend our type system to the let-polymorphic type system, the ML-style polymorphism.

¹Polymorphism refers to the language mechanisms that allow a single part of a program to be used with different types in different contexts

What went wrong?

```
let f = proc (x) x in
  if (f (iszero (0))) then (f 11) else (f 22)
```

- We assign type $t \rightarrow t$ to f , generating the constraint that the argument and return types are the same.
- Intuitively, the program can be well typed because the all usages of f satisfy the required constraint:
 - ▶ In $(f \text{ (iszero 0)})$, we can assign $\text{bool} \rightarrow \text{bool}$ to f .
 - ▶ In $(f \text{ 11})$ and $(f \text{ 22})$, we can assign $\text{int} \rightarrow \text{int}$ to f .
- However, our type checking algorithm uses the same type variable t in both cases and generates the spurious constraint that $\text{bool} = \text{int}$.
- Any idea to fix this problem?

A Simple Solution

Associate a *different* variable t with each use of f . This is easily accomplished by substituting the body of f for each occurrence of f . For example, convert the program

```
let f = proc (x) x in
  if (f (iszero (0))) then (f 11) else (f 22)
```

into the following before type-checking:

```
if ((proc (x) x) (iszero (0)))
then ((proc (x) x) 11)
else ((proc (x) x) 22)
```

which is accepted by our type system as we can generate different type variables for different copies of the procedure.

Typing Rule

Instead of the ordinary typing rule for let:

$$\frac{\Gamma \vdash E_1 : t_1 \quad [x \mapsto t_1]\Gamma \vdash E_2 : t_2}{\Gamma \vdash \text{let } x = E_1 \text{ in } E_2 : t_2}$$

we used the new typing rule:

$$\frac{\Gamma \vdash [x \mapsto E_1]E_2 : t_2}{\Gamma \vdash \text{let } x = E_1 \text{ in } E_2 : t_2}$$

Here, $[x \mapsto E_1]E_2$ denotes an expression obtained by replacing each occurrence of x by E_1 in E_2 .

The corresponding algorithm for generating type equation:

$$\mathcal{V}(\Gamma, \text{let } x = e_1 \text{ in } e_2, t) = \mathcal{V}(\Gamma, [x \mapsto e_1]e_2, t)$$

The ordinary unification algorithm does the rest.

Flaws

This simplistic method has some flaws that need to be addressed before we can use it in practice.

- 1 Unused definitions are not type-checked, so a program like
`let x = <unsafe code> in 5`
will pass the type-checker. (This can be easily fixed. See Exercise 1)
- 2 The method is not efficient if the body of `let` contains many occurrences of the bound variables:

```
let a = <complex code> in
  let b = a + a in
    let c = b + b in
      let d = c + c in
        ...
```

The typing rule can cause the type-checker to perform an amount of work that is exponential in the size of the original code.

Exercise 1

Fix the typing rule and \mathcal{V} to repair the first problem.

We can fix the problem by adding a premise to the typing rule:

$$\frac{\Gamma \vdash [x \mapsto E_1]E_2 : t_2 \quad \Gamma \vdash E_1 : t_1}{\Gamma \vdash \text{let } x = E_1 \text{ in } E_2 : t_2}$$

and a corresponding premise to the algorithm:

$$\mathcal{V}(\Gamma, \text{let } x = e_1 \text{ in } e_2, t) = \mathcal{V}(\Gamma, e_1, \alpha) \wedge \mathcal{V}(\Gamma, [x \mapsto e_1]e_2, t) \text{ (new } \alpha)$$

Let-Polymorphic Type Checking Algorithm

To avoid the re-computation, practical implementations of languages with let-polymorphism use a more clever algorithm. In outline, the type-checking of

$$\text{let } x = e_1 \text{ in } e_2$$

proceeds as follows:

- We find the most general type t of e_1 by running the ordinary type-checking algorithm (i.e., compute $\mathcal{U}(\mathcal{V}(\Gamma, e_1, t))$ where Γ is the type environment embracing e_1).
- We *generalize* any variables remaining in the type, obtaining the *type scheme* $\forall \alpha_1 \dots \alpha_n. t$, where $\alpha_1 \dots \alpha_n$ appear in t .
- We extend the type environment to record the type scheme for the bound variable x , and start type-checking e_2
- Each time we encounter an occurrence of x , we generate fresh type variables $\beta_1 \dots \beta_n$ and use them to instantiate the type scheme.

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} \text{ 1 in } \underbrace{(f \text{ 1})}_{t_2} + \underbrace{(f \text{ true})}_{t_3}}_{t_0}}_{t_1}$$

	Equations	Substitution
t_f	$= \forall t_x. t_x \rightarrow \text{int}$	
t_1	$= \text{int}$	
t_2	$= \text{int}$	
t_3	$= \text{int}$	
t_f	$= \text{int} \rightarrow t_2$	
t_f	$= \text{bool} \rightarrow t_3$	
t_0	$= t_1$	

$$\mathcal{U}(\mathcal{V}(\emptyset, \text{proc } (x) \text{ 1}, t_4)) = t_x \rightarrow \text{int}.$$

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_0}$$

Equations	Substitution
$t_f = \text{int} \rightarrow t_2$	$t_f = \forall t_x. t_x \rightarrow \text{int}$
$t_f = \text{bool} \rightarrow t_3$	$t_1 = \text{int}$
$t_0 = t_1$	$t_2 = \text{int}$
	$t_3 = \text{int}$

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_0}}$$

Equations	Substitution
$\beta_1 \rightarrow \text{int} = \text{int} \rightarrow t_2$	$t_f = \forall t_x. t_x \rightarrow \text{int}$
$t_f = \text{bool} \rightarrow t_3$	$t_1 = \text{int}$
$t_0 = t_1$	$t_2 = \text{int}$
	$t_3 = \text{int}$

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_0}}$$

Equations	Substitution
$\beta_1 = \text{int}$	$t_f = \forall t_x. t_x \rightarrow \text{int}$
$\text{int} = t_2$	$t_1 = \text{int}$
$t_f = \text{bool} \rightarrow t_3$	$t_2 = \text{int}$
$t_0 = t_1$	$t_3 = \text{int}$

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_0}$$

Equations	Substitution
	$t_f = \forall t_x. t_x \rightarrow \text{int}$
	$t_1 = \text{int}$
	$t_2 = \text{int}$
	$t_3 = \text{int}$
	$\beta_1 = \text{int}$
	$t_2 = \text{int}$
$t_f = \text{bool} \rightarrow t_3$	
$t_0 = t_1$	

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_1}}_{t_0}$$

Equations	Substitution
	$t_f = \forall t_x. t_x \rightarrow \text{int}$
	$t_1 = \text{int}$
	$t_2 = \text{int}$
	$t_3 = \text{int}$
	$\beta_1 = \text{int}$
	$t_2 = \text{int}$
$\beta_2 \rightarrow \text{int} = \text{bool} \rightarrow t_3$	
$t_0 = t_1$	

Example 1

$$\underbrace{\text{let } \underbrace{(f)}_{t_f} = \text{proc } \underbrace{(x)}_{t_x} 1 \text{ in } \underbrace{(f\ 1)}_{t_2} + \underbrace{(f\ \text{true})}_{t_3}}_{t_0}$$

Equations	Substitution
	$t_f = \forall t_x. t_x \rightarrow \text{int}$
	$t_1 = \text{int}$
	$t_2 = \text{int}$
	$t_3 = \text{int}$
	$\beta_1 = \text{int}$
	$t_2 = \text{int}$
	$\beta_2 = \text{bool}$
	$t_3 = \text{int}$
	$t_0 = \text{int}$

Example 2

let $\underbrace{f}_{t_f} = \text{proc } (\underbrace{x}_{t_x}) \text{ in if } (\underbrace{f \text{ true}}_{t_2}) \text{ then } 1 \text{ else } (\underbrace{(f f) 2}_{t_4})$

$\underbrace{\hspace{15em}}_{t_0}$

Equations	Substitution
$t_f = \forall t_x. t_x \rightarrow t_x$	
$t_2 = \text{bool}$	
$t_3 = \text{int}$	
$t_4 = \text{int} \rightarrow t_3$	
$t_f = \text{bool} \rightarrow t_2$	
$t_f = t_f \rightarrow t_4$	
$t_0 = t_3$	

$$\mathcal{U}(\mathcal{V}(\emptyset, \text{proc } (x) x, t_1)) = t_x \rightarrow t_x.$$

Example 2

let $\underbrace{f}_{t_f} = \text{proc } (\underbrace{x}_{t_x}) \underbrace{x}_{t_1} \text{ in if } (\underbrace{f \text{ true}}_{t_2}) \text{ then } 1 \text{ else } (\underbrace{(f f) 2}_{t_4})$

$\underbrace{\hspace{15em}}_{t_0}$

Equations

Substitution

$$\begin{aligned}\beta_1 \rightarrow \beta_1 &= \text{bool} \rightarrow \text{bool} \\ t_f &= t_f \rightarrow t_4 \\ t_0 &= t_3\end{aligned}$$

$$\begin{aligned}t_f &= \forall t_x. t_x \rightarrow t_x \\ t_2 &= \text{bool} \\ t_3 &= \text{int} \\ t_4 &= \text{int} \rightarrow \text{int}\end{aligned}$$

Example 2

let $\underbrace{f}_{t_f} = \text{proc } (\underbrace{x}_{t_x}) \text{ in if } (\underbrace{f \text{ true}}_{t_2}) \text{ then } 1 \text{ else } (\underbrace{(f f) 2}_{t_4})$

$\underbrace{\hspace{15em}}_{t_0}$

Equations

$$\begin{aligned} \beta_2 \rightarrow \beta_2 &= (\beta_3 \rightarrow \beta_3) \rightarrow t_4 \\ t_0 &= t_3 \end{aligned}$$

Substitution

$$\begin{aligned} t_f &= \forall t_x. t_x \rightarrow t_x \\ t_2 &= \text{bool} \\ t_3 &= \text{int} \\ t_4 &= \text{int} \rightarrow \text{int} \\ \beta_1 &= \text{bool} \end{aligned}$$

Example 2

let $\underbrace{f}_{t_f} = \text{proc } (\underbrace{x}_{t_x}) \underbrace{x}_{t_1} \text{ in if } (\underbrace{f \text{ true}}_{t_2}) \text{ then } 1 \text{ else } (\underbrace{(f f) 2}_{t_4})$

$\underbrace{\hspace{15em}}_{t_0}$

Equations	Substitution
	$t_f = \forall t_x. t_x \rightarrow t_x$
	$t_2 = \text{bool}$
	$t_3 = \text{int}$
	$t_4 = \text{int} \rightarrow \text{int}$
	$\beta_1 = \text{bool}$
	$\beta_2 = \beta_3 \rightarrow \beta_3$
$\beta_3 \rightarrow \beta_3 = \text{int} \rightarrow \text{int}$	
$t_0 = t_3$	

Summary

- We extended our type system (called *simple type system*) to *let-polymorphic type system*, the core of ML type system.
- The extension is conservative:

$$\Gamma \vdash_{simple} E : T \implies \Gamma \vdash_{poly} E : T$$

Let-polymorphic type system accepts all programs acceptable by the simple type system.