

ENE4014: Programming Languages

Lecture 15 — Automatic Type Inference (3)

Woosuk Lee
2024 Spring

Finding a Solution of Type Equations

Find the values of type variables that make all the equations true.

$$\underbrace{\underbrace{\underbrace{\underbrace{\text{proc } (f)}_{t_f} \text{ proc } (x)}_{t_x} ((f \ 3) - (f \ x))}_{t_2}}_{t_1}}_{t_0}$$

| Equations | Solution |
|------------------------------------|---|
| $t_0 = t_f \rightarrow t_1$ | $t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (\text{int} \rightarrow \text{int})$ |
| $t_1 = t_x \rightarrow t_2$ | $t_1 = \text{int} \rightarrow \text{int}$ |
| $t_3 = \text{int}$ | $t_2 = \text{int}$ |
| $t_4 = \text{int}$ | $t_3 = \text{int}$ |
| $t_2 = \text{int}$ | $t_4 = \text{int}$ |
| $t_f = \text{int} \rightarrow t_3$ | $t_f = \text{int} \rightarrow \text{int}$ |
| $t_f = t_x \rightarrow t_4$ | $t_x = \text{int}$ |

Static type systems find such a solution using *unification algorithm*.

Example 1

The calculation is split into equations to be solved and substitution found so far. Initially, the substitution is empty:

| | Equations | Substitution |
|-------|--------------------------------|--------------|
| t_0 | $= t_f \rightarrow t_1$ | |
| t_1 | $= t_x \rightarrow t_2$ | |
| t_3 | $= \text{int}$ | |
| t_4 | $= \text{int}$ | |
| t_2 | $= \text{int}$ | |
| t_f | $= \text{int} \rightarrow t_3$ | |
| t_f | $= t_x \rightarrow t_4$ | |

Example 1

Consider each equation in turn. If the equation's left-hand side is a variable, move it to the substitution:

| Equations | Substitution |
|------------------------------------|-----------------------------|
| $t_1 = t_x \rightarrow t_2$ | $t_0 = t_f \rightarrow t_1$ |
| $t_3 = \text{int}$ | |
| $t_4 = \text{int}$ | |
| $t_2 = \text{int}$ | |
| $t_f = \text{int} \rightarrow t_3$ | |
| $t_f = t_x \rightarrow t_4$ | |

Example 1

Move the next equation to the substitution and propagate the information to the existing substitution (i.e., substitute the right-hand side for each occurrence of t_1):

| Equations | Substitution |
|------------------------------------|---|
| $t_3 = \text{int}$ | $t_0 = t_f \rightarrow (t_x \rightarrow t_2)$ |
| $t_4 = \text{int}$ | $t_1 = t_x \rightarrow t_2$ |
| $t_2 = \text{int}$ | |
| $t_f = \text{int} \rightarrow t_3$ | |
| $t_f = t_x \rightarrow t_4$ | |

Example 1

Same for the next three equations:

| Equations | Substitution |
|------------------------------------|---|
| $t_4 = \text{int}$ | $t_0 = t_f \rightarrow (t_x \rightarrow t_2)$ |
| $t_2 = \text{int}$ | $t_1 = t_x \rightarrow t_2$ |
| $t_f = \text{int} \rightarrow t_3$ | $t_3 = \text{int}$ |
| $t_f = t_x \rightarrow t_4$ | |

| Equations | Substitution |
|------------------------------------|---|
| $t_2 = \text{int}$ | $t_0 = t_f \rightarrow (t_x \rightarrow t_2)$ |
| $t_f = \text{int} \rightarrow t_3$ | $t_1 = t_x \rightarrow t_2$ |
| $t_f = t_x \rightarrow t_4$ | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |

| Equations | Substitution |
|------------------------------------|--|
| $t_f = \text{int} \rightarrow t_3$ | $t_0 = t_f \rightarrow (t_x \rightarrow \text{int})$ |
| $t_f = t_x \rightarrow t_4$ | $t_1 = t_x \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |

Example 1

Consider the next equation $t_f = \text{int} \rightarrow t_3$. The equation contains t_3 , which is already bound to int in the substitution. Substitute int for t_3 in the equation. This is called *applying* the substitution to the equation.

| Equations | Substitution |
|---|--|
| $t_f = \text{int} \rightarrow \text{int}$ | $t_0 = t_f \rightarrow (t_x \rightarrow \text{int})$ |
| $t_f = t_x \rightarrow t_4$ | $t_1 = t_x \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |

Move the resulting equation to the substitution and update it.

| Equations | Substitution |
|-----------------------------|--|
| $t_f = t_x \rightarrow t_4$ | $t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$ |
| | $t_1 = t_x \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |
| | $t_f = \text{int} \rightarrow \text{int}$ |

Example 1

Apply the substitution to the equation:

| Equations | Substitution |
|--|--|
| $\text{int} \rightarrow \text{int} = t_x \rightarrow \text{int}$ | $t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$ |
| | $t_1 = t_x \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |
| | $t_f = \text{int} \rightarrow \text{int}$ |

If neither side of the equation is a variable, simplify the equation by yielding two new equations:

| Equations | Substitution |
|---------------------------|--|
| $\text{int} = t_x$ | $t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (t_x \rightarrow \text{int})$ |
| $\text{int} = \text{int}$ | $t_1 = t_x \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |
| | $t_f = \text{int} \rightarrow \text{int}$ |

Example 1

Switch the sides of the first equation and move it to the substitution:

| Equations | Substitution |
|---------------------------|---|
| $\text{int} = \text{int}$ | $t_0 = (\text{int} \rightarrow \text{int}) \rightarrow (\text{int} \rightarrow \text{int})$ |
| | $t_1 = \text{int} \rightarrow \text{int}$ |
| | $t_3 = \text{int}$ |
| | $t_4 = \text{int}$ |
| | $t_2 = \text{int}$ |
| | $t_f = \text{int} \rightarrow \text{int}$ |
| | $t_x = \text{int}$ |

The final substitution is the solution of the original equations.

Example 2

$$\text{proc } \underbrace{(f)}_{t_f} \underbrace{(f \ 11)}_{t_1}$$

t_0

$$t_0 = t_f \rightarrow t_1$$

$$t_f = \text{int} \rightarrow t_1$$

Example 2

1

| Equations | Substitution |
|------------------------------------|--------------|
| $t_0 = t_f \rightarrow t_1$ | |
| $t_f = \text{int} \rightarrow t_1$ | |

2

| Equations | Substitution |
|------------------------------------|-----------------------------|
| $t_f = \text{int} \rightarrow t_1$ | $t_0 = t_f \rightarrow t_1$ |

3

| Equations | Substitution |
|-----------|--|
| | $t_0 = (\text{int} \rightarrow t_1) \rightarrow t_1$ |
| | $t_f = \text{int} \rightarrow t_1$ |

The type is *polymorphic* in t_1 .

Example 3

if \underbrace{x}_{t_x} then $\underbrace{(x - 1)}_{t_1}$ else 0

$\underbrace{\hspace{15em}}_{t_0}$

$t_x = \text{bool}$

$t_1 = t_0$

int = t_0

$t_x = \text{int}$

$t_1 = \text{int}$

Example 3

The equations have no solutions because, during the unification algorithm, we encounter the following contradictory state:

| Equations | Substitution |
|----------------------------|---------------------|
| $\text{bool} = \text{int}$ | $t_x = \text{bool}$ |
| $t_1 = \text{int}$ | $t_1 = \text{int}$ |
| | $t_0 = \text{int}$ |

Because `bool` and `int` cannot be equal, there is no solution to the equations.

Example 4

$$\text{proc } \underbrace{(f)}_{t_f} \underbrace{(\text{iszero } \underbrace{(f f)}_{t_2})}_{t_1}$$
$$\underbrace{\hspace{15em}}_{t_0}$$
$$t_0 = t_f \rightarrow t_1$$
$$t_1 = \text{bool}$$
$$t_2 = \text{int}$$
$$t_f = t_f \rightarrow t_2$$

Example 4

Solving as usual, we encounter a problem:

| Equations | Substitution |
|------------------------------------|-------------------------------------|
| $t_f = t_f \rightarrow \text{int}$ | $t_0 = t_f \rightarrow \text{bool}$ |
| | $t_1 = \text{bool}$ |
| | $t_2 = \text{int}$ |

- There is no type t_f that satisfies the equation, because the right-hand side of the equation is always larger than the left.
- If we ever deduce an equation of the form $t = \dots t \dots$ where the type variable t occurs in the right-hand side, we must conclude that there is no solution. This is called *occurrence check*.

Unification Algorithm

For each equation in turn,

- Apply the current substitution to the equation.
- If the equation is always true (e.g. $\text{int} = \text{int}$), discard it.
- If the left- and right-hand sides are contradictory (e.g. $\text{bool} = \text{int}$), the algorithm fails.
- If neither side is a variable (e.g. $\text{int} \rightarrow t_1 = t_2 \rightarrow \text{bool}$), simplify the equation, which eventually generates an equation whose left- or right-hand side is a variable.
- If the left-hand side is not a variable, switch the sides.
- If the left-hand side variable occurs in the right-hand side, the algorithm fails.
- Otherwise, move it to the substitution and substitute the right-hand side for each occurrence of the variable in the substitution.

Exercise 1

let $x = 4$ in $(x \ 3)$

Exercise 2

let $f = \text{proc } (z) z \text{ in proc } (x) ((f x) - 1)$

Exercise 3

let $p = \text{iszero } 1$ in if p then 88 else 99

Exercise 4

```
let f = proc (x) x in if (f (iszero0)) then (f 11) else (f 22)
```

Substitution

Solutions of type equations are represented by substitution:

$$S \in \mathit{Subst} = \mathit{TyVar} \rightarrow \mathit{T}$$

Applying a substitution to a type:

$$\begin{aligned} S(\mathit{int}) &= \mathit{int} \\ S(\mathit{bool}) &= \mathit{bool} \\ S(\alpha) &= \begin{cases} t & \text{if } \alpha \mapsto t \in S \\ \alpha & \text{otherwise} \end{cases} \\ S(T_1 \rightarrow T_2) &= S(T_1) \rightarrow S(T_2) \end{aligned}$$

Example

Applying the substitution

$$S = \{t_1 \mapsto \text{int}, t_2 \mapsto \text{int} \rightarrow \text{int}\}$$

to to the type $(t_1 \rightarrow t_2) \rightarrow (t_3 \rightarrow \text{int})$:

$$\begin{aligned} & S((t_1 \rightarrow t_2) \rightarrow (t_3 \rightarrow \text{int})) \\ &= S(t_1 \rightarrow t_2) \rightarrow S(t_3 \rightarrow \text{int}) \\ &= (S(t_1) \rightarrow S(t_2)) \rightarrow (S(t_3) \rightarrow S(\text{int})) \\ &= (\text{int} \rightarrow (\text{int} \rightarrow \text{int})) \rightarrow (t_3 \rightarrow \text{int}) \end{aligned}$$

Unification

Update the current substitution with equality $t_1 \doteq t_2$.

unify : $T \times T \times \text{Subst} \rightarrow \text{Subst}$

$$\mathbf{unify}(\text{int}, \text{int}, S) = S$$

$$\mathbf{unify}(\text{bool}, \text{bool}, S) = S$$

$$\mathbf{unify}(\alpha, \alpha, S) = S$$

$$\mathbf{unify}(\alpha, t, S) = \begin{cases} \text{fail} & \alpha \text{ occurs in } t \\ \text{extend } S \text{ with } \alpha \doteq t & \text{otherwise} \end{cases}$$

$$\mathbf{unify}(t, \alpha, S) = \mathbf{unify}(\alpha, t, S)$$

$$\mathbf{unify}(t_1 \rightarrow t_2, t'_1 \rightarrow t'_2, S) = \text{let } S' = \mathbf{unify}(t_1, t'_1, S) \text{ in} \\ \text{let } S'' = \mathbf{unify}(S'(t_2), S'(t'_2), S') \text{ in} \\ S''$$

$$\mathbf{unify}(-, -, -) = \text{fail}$$

Exercises

- $\text{unify}(\alpha, \text{int} \rightarrow \text{int}, \emptyset) =$
- $\text{unify}(\alpha, \text{int} \rightarrow \alpha, \emptyset) =$
- $\text{unify}(\alpha \rightarrow \beta, \text{int} \rightarrow \text{int}, \emptyset) =$
- $\text{unify}(\alpha \rightarrow \beta, \text{int} \rightarrow \alpha, \emptyset) =$

Solving Equations

unifyall : $TyEqn \rightarrow Subst \rightarrow Subst$

unifyall(\emptyset, S) = S

unifyall(($t_1 \doteq t_2$) \wedge u, S) = let $S' = \mathbf{unify}(S(t_1), S(t_2), S)$
in **unifyall**(u, S')

Let \mathcal{U} be the final unification algorithm:

$\mathcal{U}(u) = \mathbf{unifyall}(u, \emptyset)$

typeof : $E \rightarrow T$

The final type inference algorithm that composes equation derivation (\mathcal{V}) and equation solving (\mathcal{U}):

$$\begin{aligned} \mathbf{typeof}(E) = & \\ & \mathbf{let } S = \mathcal{U}(\mathcal{V}(\emptyset, E, \alpha)) \quad (\text{new } \alpha) \\ & \mathbf{in } S(\alpha) \end{aligned}$$

Examples

- `typeof((proc (x) x) 1)`

Examples

- `typeof((proc (x) x) 1)`
- `typeof(let $x = 1$ in proc(y) ($x + y$))`

Summary

Automatic type inference:

- derive type equations from the program text, and
- solve the equations by unification algorithm.